

# NEW RESULTS OF LARGE-ORDER INVESTIGATION IN DYNAMIC MODELS

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Standard models of critical dynamics with Gibbsian static limit may be described by the generic Langevin equation

$$\frac{\partial \varphi_a}{\partial t} + (\alpha_{ab} + \beta_{ab}) \frac{\delta S}{\delta \varphi_b} = \xi_a, \quad (2.1)$$

$S$  is the static "action" (effective Hamiltonian).  $\xi$  is a Gaussian random field,  $\langle \xi \rangle = 0$

$$\langle \xi_a(t, \mathbf{x}) \xi_b(t', \mathbf{x}') \rangle = 2\alpha_{ab} \delta(t - t') \delta(\mathbf{x} - \mathbf{x}') \quad (2.2)$$

where:

$$\alpha^\top = \alpha, \quad \beta^\top = -\beta, \quad \sum_{\alpha} \frac{\delta \beta_{ab}}{\delta \varphi_a} = 0. \quad (2.3)$$

Let us list the static actions  $S$  and the parameters  $\alpha$  and  $\beta$  for models A-H:

Model A:

$$S = \frac{1}{2} \nabla \phi \nabla \phi + \frac{g}{4!} \phi^4. \quad \alpha = D/2,$$

where the correlator  $D$  is a constant.

Model B:

$$S = \frac{1}{2} \nabla \phi \nabla \phi + \frac{g}{4!} \phi^4. \quad \alpha = -\lambda \nabla^2,$$

where  $\lambda$  is a constant.

Model C:

$$S = \frac{1}{2} (\nabla \phi)^2 + \frac{g}{4!} \phi^4 + \frac{m^2}{2} + \frac{1}{2} v_2 m \phi^2. \quad \alpha = \begin{pmatrix} \Gamma & 0 \\ 0 & -\lambda \nabla^2 \end{pmatrix},$$

where  $m$  is an additional scalar field;  $\Gamma$ ,  $\lambda$  are constants;  $v_2$  is an additional coupling constant.

Model D:

$$S = \frac{1}{2} (\nabla\phi)^2 + \frac{g}{4!} \phi^4 + \frac{m^2}{2} + \frac{1}{2} v_2 m \phi^2. \quad \alpha = \begin{pmatrix} -\lambda \nabla^2 & 0 \\ 0 & -\lambda_1 \nabla^2 \end{pmatrix},$$

where  $\lambda$  and  $\lambda_1$  are constants.

Model F:

$$S = |\nabla\psi|^2 + \frac{g}{6} |\psi|^4 + \frac{m^2}{2} + v_2 m |\psi|^2.$$

$$\alpha = \begin{pmatrix} 0 & \lambda_\psi & 0 \\ \lambda_\psi & 0 & 0 \\ 0 & 0 & -\lambda_m \nabla^2 \end{pmatrix}, \quad \beta = \begin{pmatrix} 0 & iv_3 & iv_4 \psi \\ -iv_3 & 0 & -iv_4 \psi^* \\ -iv_4 \psi^* & iv_4 \psi & 0 \end{pmatrix},$$

where  $\psi$  is a complex-valued field;  $\lambda_\psi$ ,  $\lambda_m$  are constants;  $v_i$  ( $i = 2, 3, 4$ ) are additional coupling constants.

Model E is F model with  $v_2 = v_3 = 0$ .

Model G: There are two real vector fields forming the field  $\varphi$  by prescription:  $\varphi_a = \phi_a$  and  $\varphi_{3+a} = m_a$ , where  $a = 1, 2, 3$ . Then

$$S = \frac{1}{2} (\nabla\phi)^2 + \frac{g}{4!} \phi^4 + \frac{m^2}{2}, \quad \alpha = \begin{pmatrix} \lambda_\phi & 0 \\ 0 & -\lambda_m \nabla^2 \end{pmatrix},$$

$$\beta_{ab} = 0, \quad \beta_{a3+b} = v_2 \epsilon_{abc} \phi_c, \quad \beta_{3+a3+b} = v_2 \epsilon_{abc} m_c,$$

$a, b, c = 1, 2, 3$ .

Model H:

$$S = \frac{1}{2} (\nabla\phi)^2 + \frac{g}{4!} \phi^4 + \frac{c}{2} \mathbf{v}_\perp^2,$$

$$\alpha = \begin{pmatrix} -\lambda_\phi \nabla^2 & 0 \\ 0 & -\lambda_v \nabla^2 \end{pmatrix}, \quad \beta = \begin{pmatrix} 0 & v_2 \vec{\nabla} \phi \\ -v_2 \overleftarrow{\nabla} \phi & 0 \end{pmatrix},$$

where the transverse projection operator for the vector field  $\mathbf{v}$  is implied;  $\lambda_\psi$ ,  $\lambda_m$ ,  $v_2$  are constants.

In the MSR approach the dynamic action for the model (2.1)– (2.3) may be written symbolically [4] as

$$\bar{S} = -\varphi'_a \alpha_{ab} \varphi'_b + \varphi'_a \left[ \frac{\partial \varphi_a}{\partial t} + (\alpha_{ab} + \beta_{ab}) \frac{\delta S}{\delta \varphi_b} \right]. \quad (2.4)$$

the boundary conditions  $\varphi(t = -\infty) = 0$  and arbitrary  $\varphi(T)$ ,  $\varphi'(t = -\infty)$ ,  $\varphi'(T)$ .  $T$  is a maximal time in the consideration.

The  $N$ th order contribution to perturbation expansion in  $g$  of the



## $k$ -point Green function

$$G_k^{[M]} = \frac{1}{2\pi i} \oint \frac{du}{u} \frac{\iint \mathcal{D}\varphi \mathcal{D}\varphi' \Phi_{a_1}(t_1, \mathbf{x}_1) \dots \Phi_{a_k}(t_k, \mathbf{x}_k) e^{-\bar{S}} - N \ln u}{\iint \mathcal{D}\varphi \mathcal{D}\varphi' e^{-\bar{S}_0}}, \quad (3.1)$$

$\Phi = \{\varphi, \varphi'\}$ . The stationarity equations of the method of steepest descent

$$\frac{\delta \bar{S}}{\delta \varphi_a} = -\frac{\partial \varphi'_a}{\partial t} + \varphi'_b (\alpha_{bc} + \beta_{bc}) \frac{\delta^2 S}{\delta \varphi_c \delta \varphi_a} + \varphi'_b \frac{\delta \beta_{bc}}{\delta \varphi_a} \frac{\delta S}{\delta \varphi_c} = 0, \quad (3.2)$$

$$\frac{\delta \bar{S}}{\delta \varphi'_a} = -2\alpha_{ab} \varphi'_b + \frac{\partial \varphi_a}{\partial t} + (\alpha_{ab} + \beta_{ab}) \frac{\delta S}{\delta \varphi_b} = 0, \quad (3.3)$$

with the boundary condition

$$\varphi'(T, \mathbf{x}) = 0. \quad (3.4)$$

The dynamic instanton  $\varphi_D$  for the basic field is the nontrivial solution of the equation

$$-\frac{\partial \varphi_a}{\partial t} + (\alpha_{ab} - \beta_{ab}) \frac{\delta S}{\delta \varphi_b} = 0. \quad (3.5)$$

$\varphi_D(T, \mathbf{x}) = \varphi_{st}(\mathbf{x})$ , where  $\varphi_{st}$  is the static instanton solution for the static action  $S$ . An iterative solution of the instanton equation (3.5) exists. Then

$$\bar{S}(\varphi_D, \varphi'_D) = S(\varphi_{st}).$$

Thus the dynamic model at leading order in  $N$  are determined by the static instanton solution which leads to

$$F^{[M]} = C N! a_M^N N^b, \quad (3.6)$$



The developed turbulence is described by the equation


$$\partial_t \mathbf{v} - \nu \Delta \mathbf{v} + (\mathbf{v} \partial) \mathbf{v} = \xi,$$

for  $d = 2$ :  $\langle \xi \xi \rangle = \text{const} \Delta \delta(\mathbf{x} - \mathbf{x}') \delta(t - t')$ . Then the static limit exists, it is Gibbsian  $\exp(-v^2/2)$ . There is no nonzero static instanton.

There is a model with derivative in the interaction.

The advection of a passive scalar field  $\varphi(\mathbf{x}, t)$  is described by a stochastic equation:

$$\partial_t \varphi - \nu \Delta \varphi + g \partial_i (\mathbf{v}_i \varphi) = \xi(\mathbf{x}, t), \quad (5.1)$$

where  $\nu$  is a molecular diffusivity coefficient,  $\xi$  is an Gaussian scalar noise,  $\mathbf{v}(\mathbf{x}, t)$  is a velocity field. The field  $\mathbf{v}(\mathbf{x}, t)$  obeys a Gaussian 

## distribution

$$\mathbf{D}_v^{ij}(\mathbf{x} - \mathbf{x}') \equiv \langle \mathbf{v}_i(\mathbf{x}, t) \mathbf{v}_j(\mathbf{x}', t') \rangle = \quad (5.2)$$

$$D_0 \delta(t - t') \int \frac{d\mathbf{k}}{(2\pi)^d} \frac{P_{ij}^\perp(\mathbf{k}) + \alpha P_{ij}^\parallel(\mathbf{k})}{(\mathbf{k}^2 + m^2)^{\beta(\epsilon)}} e^{i\mathbf{k}(\mathbf{x} - \mathbf{x}')}.$$

or for the model with the “frozen” velocity

$$\mathbf{D}_v^{ij}(\mathbf{x} - \mathbf{x}') \equiv \langle \mathbf{v}_i(\mathbf{x}, t) \mathbf{v}_j(\mathbf{x}', t') \rangle = \quad (5.3)$$

$$D_0 \int \frac{d\mathbf{k}}{(2\pi)^d} \frac{P_{ij}^\perp(\mathbf{k}) + \alpha P_{ij}^\parallel(\mathbf{k})}{(\mathbf{k}^2 + m^2)^{\beta(\epsilon)}} e^{i\mathbf{k}(\mathbf{x} - \mathbf{x}')}.$$

## The Lagrangian variables

$$\langle \phi(\mathbf{x}, s) \phi'(\mathbf{y}, t) \rangle = \Theta(s - t) M \int_{\mathbf{c}(t)=\mathbf{y}}^{\mathbf{c}(s)=\mathbf{x}} D\mathbf{c} D\mathbf{c}' \exp \int_t^s d\tau (-\nu \mathbf{c}'^2 + (5.4) \\ i\mathbf{c}'\dot{\mathbf{c}} + ig\mathbf{c}'\mathbf{v}(\mathbf{c}, \tau)),$$

The stationarity equations in these variables have a form

$$-i\dot{\mathbf{c}}' = uv \int d\tau' \mathbf{c}' \frac{\partial D(\mathbf{c} - \mathbf{c}(\tau'))}{\partial(\mathbf{c} - \mathbf{c}(\tau'))} \mathbf{c}(\tau')', \\ i\dot{\mathbf{c}} = uv \int d\tau' D(\mathbf{c} - \mathbf{c}(\tau')) \mathbf{c}(\tau')' + 2\nu \mathbf{c}'.$$

These equations have a solution

$$\mathbf{p}(\tau) = \frac{i\dot{\mathbf{q}}(\tau)}{2\nu - g\nu D_\nu(\mathbf{q}(\tau))}, \quad \dot{\mathbf{q}}(\tau) = \frac{l_1(\mathbf{x})}{T} \sqrt{2\nu - g\nu D_\nu(\mathbf{q}(\tau))},$$

$$l_1(\mathbf{x}) = \int_0^x \frac{dz}{\sqrt{2\nu - g\nu D_\nu(z)}}$$

where  $\mathbf{p} = \mathbf{c}'_1 - \mathbf{c}'_2$ ,  $\mathbf{q} = \mathbf{c}_1 - \mathbf{c}_2$ , or

$$c'(\tau) = \frac{i\partial_\tau c(\tau)}{\nu}. \quad (5.5)$$

$$\int_0^c \frac{dy}{\int_0^{|x|} dz D(z-y)} = -\frac{u_{st}\tau}{\nu}, \quad c \equiv c_{st}(\tau). \quad (5.6)$$

The high-order asymptotes in the Kraichnan model show the convergent perturbation series.

Recently was calculated for dynamic index  $z$  in the model A

$$z = 2 + R\eta, \quad (6.1)$$

$$R = (h-1) \left[ 1 - 0.188483\epsilon + \left( -0.0999529 + \frac{b_1 n + b_0}{(n+8)^2} \right) \epsilon^2 \right] - O(\epsilon^3),$$

$$b_1 = 4.772294768, \quad b_0 = 4.9187274, \quad h = 6 \ln(4/3),$$

$$\eta = \frac{(n+2)\epsilon^2}{2(n+8)^2} \left[ 1 + \frac{\epsilon}{4(n+8)^2} (-n^2 + 56n + 272) + \right. \quad (6.2)$$

$$\left. \frac{\epsilon^2}{16(n+8)^4} (-5n^4 - 230n^3 + 1124n^2 + 17920n + 46144 - \right.$$

$$\left. 384(n+8)(5n+22)\zeta(3) \right] + O(\epsilon^5),$$

Table:  $z = z^{(k)}\epsilon^k$ .

$z_\epsilon^{(k)}$	$n = 1$	$n = 2$	$n = 3$
$z_\epsilon^{(2)}$	0.0134462	0.0145218	0.0150019
$z_\epsilon^{(3)}$	0.0110364	0.0110588	0.0105317
$z_\epsilon^{(4)}$	-0.0055807	-0.0052671	-0.0049778

**Table:** Direct calculation of  $z$  in  $\epsilon$  expansion.

$d$	$N$	$n = 1$	$n = 2$	$n = 3$
2	2	2.0537846	2.0580874	2.0600076
	3	2.1420758	2.1465574	2.1442609
	4	2.0527838	2.0622836	2.0646160
3	2	2.0134462	2.0145218	2.0150019
	3	2.0244826	2.0255806	2.0255336
	4	2.0189018	2.0203135	2.0205558



**Table:**  $z$ , PBL  $P_2^2$ -approximation ( $b = b_z + 1.5$ ).

$d$	$N$	$n = 1$	$n = 2$	$n = 3$
2	2	2.0537846	2.0580874	2.0600076
	3	2.0313245	2.0371809	2.0424021
	4	2.0195447	2.0232205	2.0260295
3	2	2.0134462	2.0145218	2.0150019
	3	2.0151405	2.0169805	2.0181449
	4	2.0111743	2.0127178	2.0136547

**Table:**  $z$ , PBL  $P_1^3$ -approximation ( $b = b_z + 1.5$ ).

$d$	$N$	$n = 1$	$n = 2$	$n = 3$
2	2	2.0537846	2.0580874	2.0600076
	3	2.1420758	2.1465574	2.1442609
	4	2.0988800	2.1045005	2.1043143
3	2	2.0134462	2.0145218	2.0150019
	3	2.0244826	2.0255806	2.0255336
	4	2.0208646	2.0220921	2.0222247

Table:  $z$  PBL  $P_{1,-1/a}^4$ -approximation ( $b = b_z$ ).

d	$N$	$n = 1$	$n = 2$	$n = 3$
2	2	2.0537846	2.0580874	2.0600076
	3	2.1420758	2.1465574	2.1442609
	4	2.1274836	2.1322986	2.1303831
3	2	2.0134462	2.0145218	2.0150019
	3	2.0244826	2.0255806	2.0255336
	4	2.0229318	2.0240719	2.0240707

Table:  $z$  CM ( $b = b_z + 1.5$ ).

$d$	$N$	$n = 1$	$n = 2$	$n = 3$
2	2	2.0064932	2.0073128	2.0078256
	3	2.0198686	2.0220831	2.0233094
	4	2.0369831	2.0406409	2.0423686
3	2	2.0032593	2.0036430	2.0038735
	3	2.0081436	2.0089683	2.0093953
	4	2.0127529	2.0138750	2.0143549

Table:  $z_{asymp}^{(k)}$  (6.7).

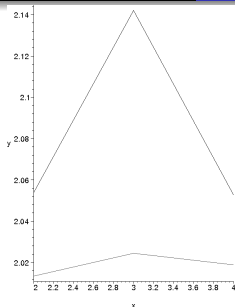
$z_{asymp}^{(k)}$	$n = 1$	$n = 2$	$n = 3$
$z_{asymp}^{(2)}$	0,0000034	0,0000011	0,0000003
$z_{asymp}^{(3)}$	-0,0000141	-0,0000051	-0,0000017
$z_{asymp}^{(4)}$	0,0000516	0,0000195	0,0000067

**Table:** Results for  $z$  ( $d=3$ ).

$d=3$	$n = 1$	$n = 2$	$n = 3$
$P_2^2$	$2.011 \pm 0,012$	$2.013 \pm 0.012$	$2.014 \pm 0.011$
$P_1^3$	$2.021 \pm 0,006$	$2.022 \pm 0.005$	$2.022 \pm 0.005$
$P_{1,-1/a}^4$	$2.023 \pm 0.006$	$2.024 \pm 0.005$	$2.024 \pm 0.005$
CM	$2.0133^{+0.011}_{-0.0}$	$2.014 \pm 0.011$	$2.014 \pm 0.011$

**Table:** Results for  $z$  ( $d=2$ ).

$d=2$	$n = 1$	$n = 2$	$n = 3$
$P_2^2$	$2.020 \pm 0,045$	$2.023 \pm 0.053$	$2.026 \pm 0.055$
$P_1^3$	$2.100 \pm 0,089$	$2.105 \pm 0.084$	$2.104 \pm 0.080$
$P_{1,-1/a}^4$	$2.130 \pm 0.089$	$2.134 \pm 0.084$	$2.132 \pm 0.080$
CM	$2.037 \pm 0.033$	$2.041 \pm 0.040$	$2.042 \pm 0.041$



## Borel-transformation

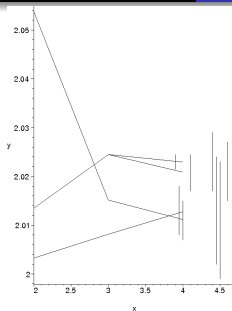
$$A(\epsilon) = \sum_{k \geq 0} A_k \epsilon^k, \quad (6.3)$$

$$B(\epsilon) = \sum_{k > 0} B_k \epsilon^k, \quad B_k = \frac{A_k}{\Gamma(k + b + 1)}, \quad (6.4)$$



$$A(\epsilon) = \int_0^{+\infty} t^b e^{-t} B(\epsilon t) dt. \quad (6.5)$$

$$u(\epsilon) = \frac{\sqrt{1 + a\epsilon} - 1}{\sqrt{1 + a\epsilon} + 1} \Leftrightarrow \epsilon(u) = \frac{4u}{a(u-1)^2}. \quad (6.6)$$



Why the results are inconsistent?

$$z_{asymp}^{(k)} \approx (h - 1)\eta_{asymp}^{(k)}. \quad (6.7)$$

$d = 3$ ,  $z = 2.1 \pm 0.1$  [16].  $z = 1.97 \pm 0.08$  [17],  
 $z = 2.04 \pm 0.03$  [18],  $z = 2.04 \pm 0.01$  [19]  $z = 2.032 \pm 0.004$  [20].  
 $d = 2$ ,  $z = 2.14 \pm 0.02$  [21],  $z = 2.13 \pm 0.03$  [22],  
 $z = 2.076 \pm 0.005$  [23],  $z = 2.24 \pm 0.04$  [24],  $z = 2.24 \pm 0.07$  [25],  
 $z = 2.16 \pm 0.04$  [26]  $z = 2.1667 \pm 0.0005$  [27].  $d = 2$   $z = 2.125$  [28].








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